

GCE Examinations  
Advanced Subsidiary / Advanced Level  
**Further Pure Mathematics**  
**Module FP3**

Paper G

**MARKING GUIDE**

This guide is intended to be as helpful as possible to teachers by providing concise solutions and indicating how marks should be awarded. There are obviously alternative methods that would also gain full marks.

Method marks (M) are awarded for knowing and using a method.

Accuracy marks (A) can only be awarded when a correct method has been used.

(B) marks are independent of method marks.



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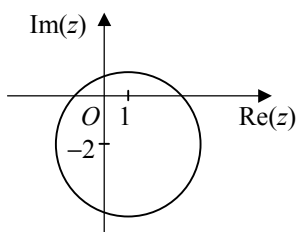
## FP3 Paper G – Marking Guide

1.  $\det \mathbf{A} = 3(0 + k) - 1(0 + 2) - 4(k - 4)$  M1  
 $= 3k - 2 - 4k + 16 = 14 - k$  A1  
 $\therefore$  singular if  $k = 14$  A1 (3)
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2.  $|-4 + 4\sqrt{3}i| = 4\sqrt{(1+3)} = 8$ ;  $\arg(-4 + 4\sqrt{3}i) = \arctan(-\sqrt{3}) = \frac{2\pi}{3}$  M1  
 $\therefore (re^{i\theta})^3 = 8e^{i\frac{2\pi}{3}}$  A1  
 $r^3 = 8$  so  $r = 2$  A1  
 $3\theta = 2n\pi + \frac{2\pi}{3}$  M1  
 $n = 0, 1, 2$  gives  $\theta = \frac{2\pi}{9}, \frac{8\pi}{9}, \frac{14\pi}{9}$  A1  
 $\therefore z = 2(\cos \frac{2\pi}{9} + i\sin \frac{2\pi}{9}), 2(\cos \frac{8\pi}{9} + i\sin \frac{8\pi}{9}), 2(\cos \frac{14\pi}{9} + i\sin \frac{14\pi}{9})$  A1 (6)
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3. assume true for  $n = k \therefore f(k) = k(k^2 + 5)$  is divisible by 6 M1  
 $f(k+1) = (k+1)[(k+1)^2 + 5]$   
 $= (k+1)(k^2 + 2k + 6)$   
 $f(k+1) - f(k) = (k+1)(k^2 + 2k + 6) - k(k^2 + 5)$  M1  
 $= k^3 + 2k^2 + 6k + k^2 + 2k + 6 - k^3 - 5k$   
 $= 3k^2 + 3k + 6 = 3k(k+1) + 6$   
 $\therefore f(k+1) = 3k(k+1) + 6 + f(k)$  A1  
 $k, (k+1)$  are consec. integers  $\therefore k(k+1)$  is div. by 2 [one must be even] M1  
 $\therefore 3k(k+1)$  is div. by 6  $\therefore f(k+1)$  is div. by 6 A1  
 $\therefore$  true for  $n = k+1$  if true for  $n = k$   
if  $n = 1$   $f(1) = 1 \times 6 = 6 \therefore f(1)$  is div. by 6  $\therefore$  true for  $n = 1$  B1  
 $\therefore$  by induction true for  $n \in \mathbb{Z}^+$  A1 (7)
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4. (a)  $|z - (1 - 2i)| = 3 \therefore$  circle, centre  $1 - 2i$ , radius 3 M1 A1



B1

- (b)  $T$ : enlargement s.f 4, centre  $O$   
giving circle, centre  $4 - 8i$ , radius 12 M1 A1  
 $U$ : translation through  $5 - i$   
giving circle centre  $6 - 3i$ , radius 3 M1 A1  
 $V$ : anticlockwise rotation through  $\frac{\pi}{2}$  about  $O$   
giving circle centre  $2 + i$ , radius 3 M1 A1 (9)
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5. (a)  $f(x) = \cos x$ ,  $f'(x) = -\sin x$ ,  $f''(x) = -\cos x$ ,  $f'''(x) = \sin x$  M1 A1  
 $f(\frac{\pi}{6}) = \frac{\sqrt{3}}{2}$ ,  $f'(\frac{\pi}{6}) = -\frac{1}{2}$ ,  $f''(\frac{\pi}{6}) = -\frac{\sqrt{3}}{2}$ ,  $f'''(\frac{\pi}{6}) = \frac{1}{2}$  A1  
 $f(x) = \frac{\sqrt{3}}{2} - \frac{1}{2}(x - \frac{\pi}{6}) + \frac{1}{2!}(-\frac{\sqrt{3}}{2})(x - \frac{\pi}{6})^2 + \frac{1}{2}(\frac{1}{3!})(x - \frac{\pi}{6})^3 + \dots$  M1  
 $f(x) = \frac{\sqrt{3}}{2} - \frac{1}{2}(x - \frac{\pi}{6}) - \frac{\sqrt{3}}{4}(x - \frac{\pi}{6})^2 + \frac{1}{12}(x - \frac{\pi}{6})^3 + \dots$  A1
- (b) if  $x = \frac{\pi}{4}$ ,  $x - \frac{\pi}{6} = \frac{\pi}{12}$  M1  
 $\therefore \cos \frac{\pi}{4} = \frac{\sqrt{3}}{2} - \frac{1}{2}(\frac{\pi}{12}) - \frac{\sqrt{3}}{4}(\frac{\pi}{12})^2 + \frac{1}{12}(\frac{\pi}{12})^3 + \dots$  M1  
 $= 0.7069$  (4dp) A1
- (c) % error =  $\frac{\cos \frac{\pi}{4} - 0.7069}{\cos \frac{\pi}{4}} \times 100\% = 0.023\%$  (2sf) M1 A1 (10)
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6. (a)  $\frac{d^3y}{dx^3} = 2x + x \frac{dy}{dx} + y - 2y \frac{dy}{dx}$  M1 A1  
 $x_0 = 0, y_0 = \frac{1}{2}$ ,  $\left(\frac{dy}{dx}\right)_0 = -1$ ;  $\left(\frac{d^2y}{dx^2}\right)_0 = 0 + 0 - \frac{1}{4} = -\frac{1}{4}$  A1  
 $\left(\frac{d^3y}{dx^3}\right)_0 = 0 + 0 + \frac{1}{2} - [2 \times \frac{1}{2} \times (-1)] = \frac{3}{2}$  A1  
 $\therefore y = \frac{1}{2} - 1x + \frac{1}{2!}(-\frac{1}{4})x^2 + \frac{1}{3!}(\frac{3}{2})x^3 + \dots$  M1  
 $y = \frac{1}{2} - x - \frac{1}{8}x^2 + \frac{1}{4}x^3 + \dots$  A1
- (b)  $x = -0.1, y \approx 0.5 + 0.1 - 0.00125 - 0.00025 = 0.5985$  A1
- (c)  $\frac{y_1 - 2y_0 + y_{-1}}{0.01} = x_0^2 + x_0y_0 - y_0^2$  M1  
 $y_1 - 2y_0 + y_{-1} = 0.01(x_0^2 + x_0y_0 - y_0^2)$   
 $y_1 = 2y_0 - y_{-1} + 0.01(x_0^2 + x_0y_0 - y_0^2)$  A1  
 $x_{-1} = -0.1, x_0 = 0, x_1 = 0.1; y_{-1} = 0.5985, y_0 = 0.5, y_1 = ?$   
 $y_1 = 1 - 0.5985 + 0.01(0 + 0 - 0.25) = 0.399$  A1 (10)
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7.	(a)	$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & -4 & 1 \\ 4 & -2 & 5 \end{vmatrix}$	
		$= \mathbf{i}(-20 + 2) - \mathbf{j}(10 - 4) + \mathbf{k}(-4 + 16) = -18\mathbf{i} - 6\mathbf{j} + 12\mathbf{k}$	M1 A1
		$ \mathbf{a} \times \mathbf{b}  =  \mathbf{a}   \mathbf{b}  \sin \theta$	
		$6\sqrt{9 + 1 + 4} = \sqrt{21}\sqrt{45} \sin \theta$	M1 A1
		$6\sqrt{7}\sqrt{2} = 3\sqrt{7}\sqrt{3}\sqrt{5} \sin \theta$	
		$\sin \theta = \frac{2\sqrt{2}}{\sqrt{15}}$ or $\frac{2}{15}\sqrt{30}$	A1
	(b)	$\mathbf{n} = 3\mathbf{i} + \mathbf{j} - 2\mathbf{k}$	M1
		$\mathbf{r} \cdot (3\mathbf{i} + \mathbf{j} - 2\mathbf{k}) = (2\mathbf{i} - \mathbf{j} + 2\mathbf{k}) \cdot (3\mathbf{i} + \mathbf{j} - 2\mathbf{k}) = 6 - 1 - 4 = 1$	M1 A1
		$\mathbf{r} \cdot (3\mathbf{i} + \mathbf{j} - 2\mathbf{k}) = 1 \therefore 3x + y - 2z - 1 = 0$	A1
	(c)	$\mathbf{r} = \mathbf{i} - 2\mathbf{j} + u(2\mathbf{j} + \mathbf{k})$	
		$u = 0, \mathbf{r} = \mathbf{i} - 2\mathbf{j}, (\mathbf{i} - 2\mathbf{j}) \cdot (3\mathbf{i} + \mathbf{j} - 2\mathbf{k}) = 3 - 2 = 1 \therefore$ in plane	M1 A1
		$u = 1, \mathbf{r} = \mathbf{i} + \mathbf{k}, (\mathbf{i} + \mathbf{k}) \cdot (3\mathbf{i} + \mathbf{j} - 2\mathbf{k}) = 3 - 2 = 1 \therefore$ in plane	M1
		two points on line in plane $\therefore$ line in plane	A1 (13)

8.	(a)	$(\mathbf{AB})(\mathbf{B}^{-1}\mathbf{A}^{-1}) = \mathbf{ABB}^{-1}\mathbf{A}^{-1} = \mathbf{AIA}^{-1} = \mathbf{AA}^{-1} = \mathbf{I}$	M1 A1
		$\therefore (\mathbf{B}^{-1}\mathbf{A}^{-1})$ is inverse of $(\mathbf{AB})$ i.e. $(\mathbf{AB})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$	M1 A1
	(b)	$S(a_1\mathbf{v}_1 + a_2\mathbf{v}_2) = S\begin{pmatrix} a_1x_1 + a_2x_2 \\ a_1y_1 + a_2y_2 \end{pmatrix}$	M1
		$= \begin{pmatrix} a_1y_1 + a_2y_2 - a_1x_1 - a_2x_2 \\ 2a_1x_1 + 2a_2x_2 + a_1y_1 + a_2y_2 \end{pmatrix}$	M1 A1
		$= \begin{pmatrix} a_1(y_1 - x_1) + a_2(y_2 - x_2) \\ a_1(2x_1 + y_1) + a_2(2x_2 + y_2) \end{pmatrix}$	M1
		$= a_1 \begin{pmatrix} y_1 - x_1 \\ 2x_1 + y_1 \end{pmatrix} + a_2 \begin{pmatrix} y_2 - x_2 \\ 2x_2 + y_2 \end{pmatrix}$	A1
		$= a_1S(\mathbf{v}_1) + a_2S(\mathbf{v}_2) \therefore S$ is a linear transformation	M1 A1
	(c)	$\mathbf{S} = \begin{pmatrix} -1 & 1 \\ 2 & 1 \end{pmatrix}, \mathbf{T} = \begin{pmatrix} 3 & 0 \\ 1 & 1 \end{pmatrix}$	M1 A1
		$\mathbf{ST} = \begin{pmatrix} -1 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 3 & 0 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -2 & 1 \\ 7 & 1 \end{pmatrix}$	M1 A1
		$\det(\mathbf{ST}) = -2 - 7 = -9$	M1
		$\therefore (\mathbf{ST})^{-1} = -\frac{1}{9} \begin{pmatrix} 1 & -1 \\ -7 & -2 \end{pmatrix}$ or $\frac{1}{9} \begin{pmatrix} -1 & 1 \\ 7 & 2 \end{pmatrix}$	A1 (17)

Total (75)

### Performance Record – FP3 Paper G

Question no.	1	2	3	4	5	6	7	8	Total
Topic(s)	singular matrix	complex nos.	proof by induction	complex trans.	Taylor series	diff. eqn., Taylor series, step-by-step	vectors	matrices, linear trans.	
Marks	3	6	7	9	10	10	13	17	75
Student									